

# Nano BPM collaboration Plans

Establishment of nano-meter resolution

Phase-I : Stabilization of two isolated systems

Phase-II : Fast feedforward/feedback tests

Demonstration of nanometer stabilization at IR.

# Nano-meter resolution

- Prototype of movers ( $Y'$  and integrated  $X, X'$ )
- 3 mover systems (control by the reference system, inertia sensor, optical anchor)
- Reference system for relative displacement of 3 BPMs
- Girder (granite table)      GM measurements
- 3 cavity BPMs       $\mu\text{m}$  Feedforward?
- Electronics of BPMs
- Readout system (ADC, VME...)

# Phase-I : Stabilization of two isolated systems

- Three Major Stabilization Schemes
- "local" : inertia sensor system (  $f > 1\text{Hz}$  )
- "remote" : optical anchor system
- "passive" : a common girder (granite table of 3m length) like as a support tube
- "remote" or "passive"

ATF beam must be the reference line!

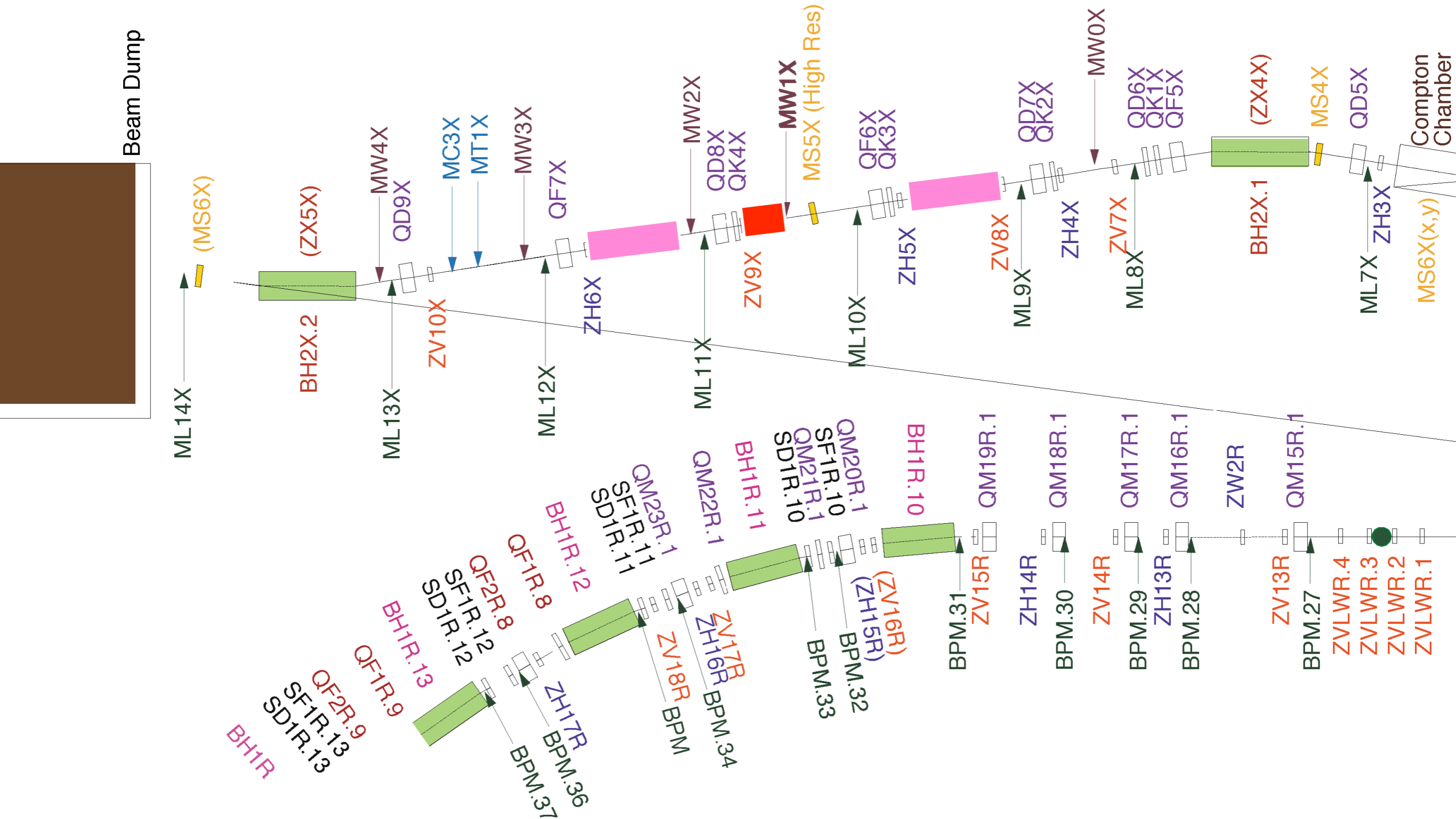
# Phase-II : Fast feedforward/ feedback tests

- Demonstration of beam control at nano-meter level.
- FEATHER and FONT systems
- Multi-train extraction

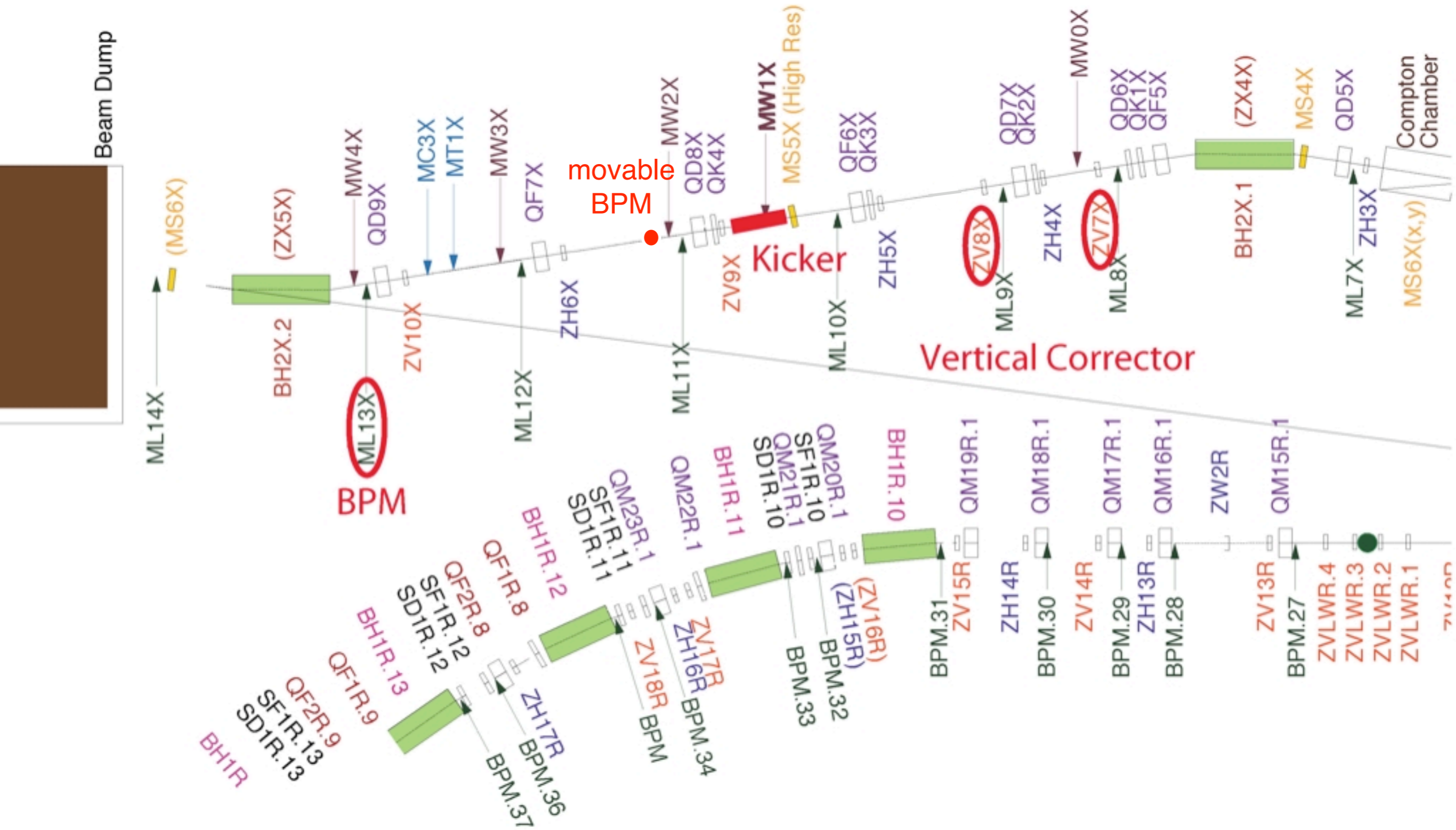
# Layout

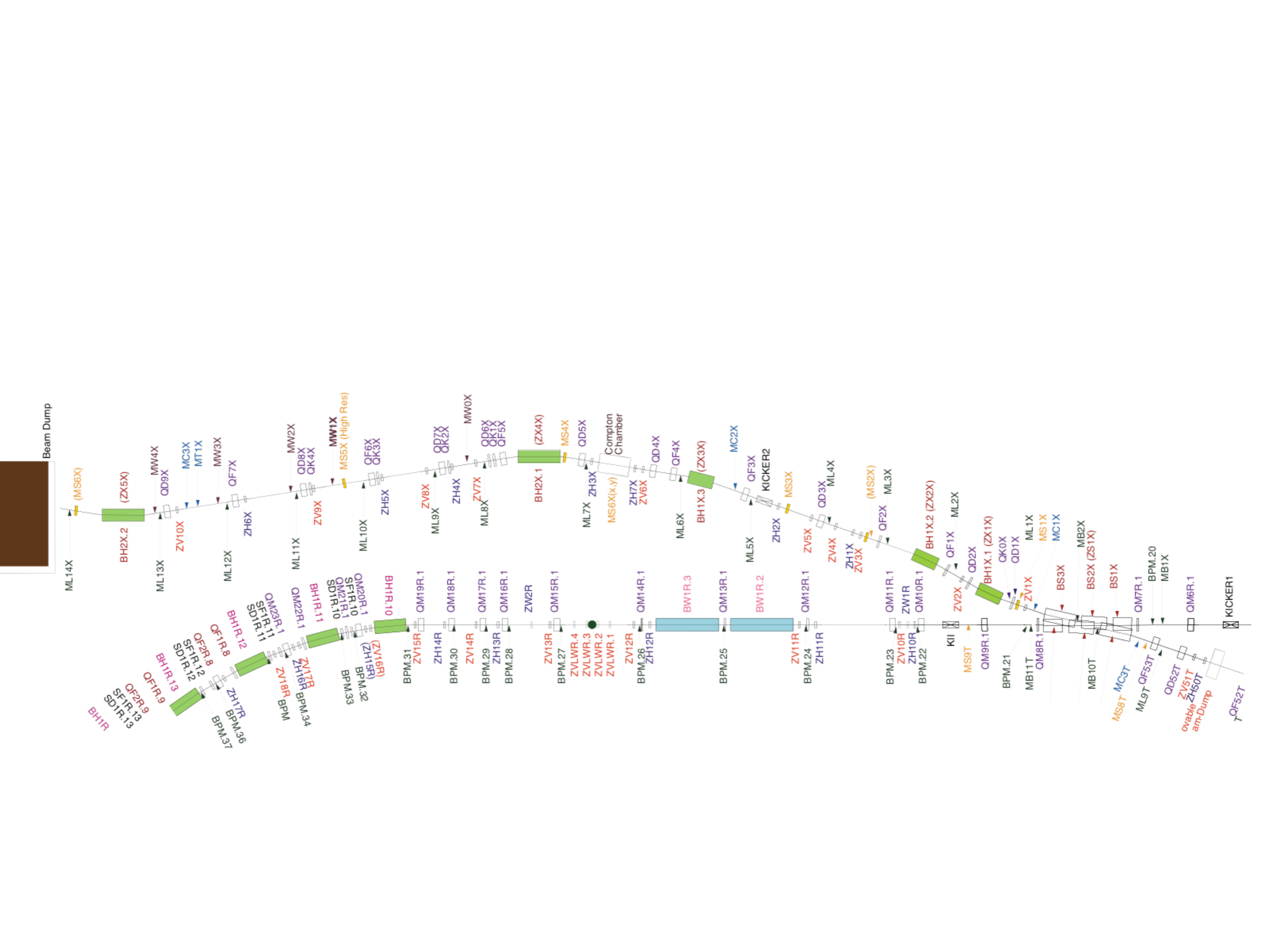
Pol.e+ area for optical anchor?

2m between Q (face to face)  
Q is 18cm thick.



# ATF Fast Feedback System





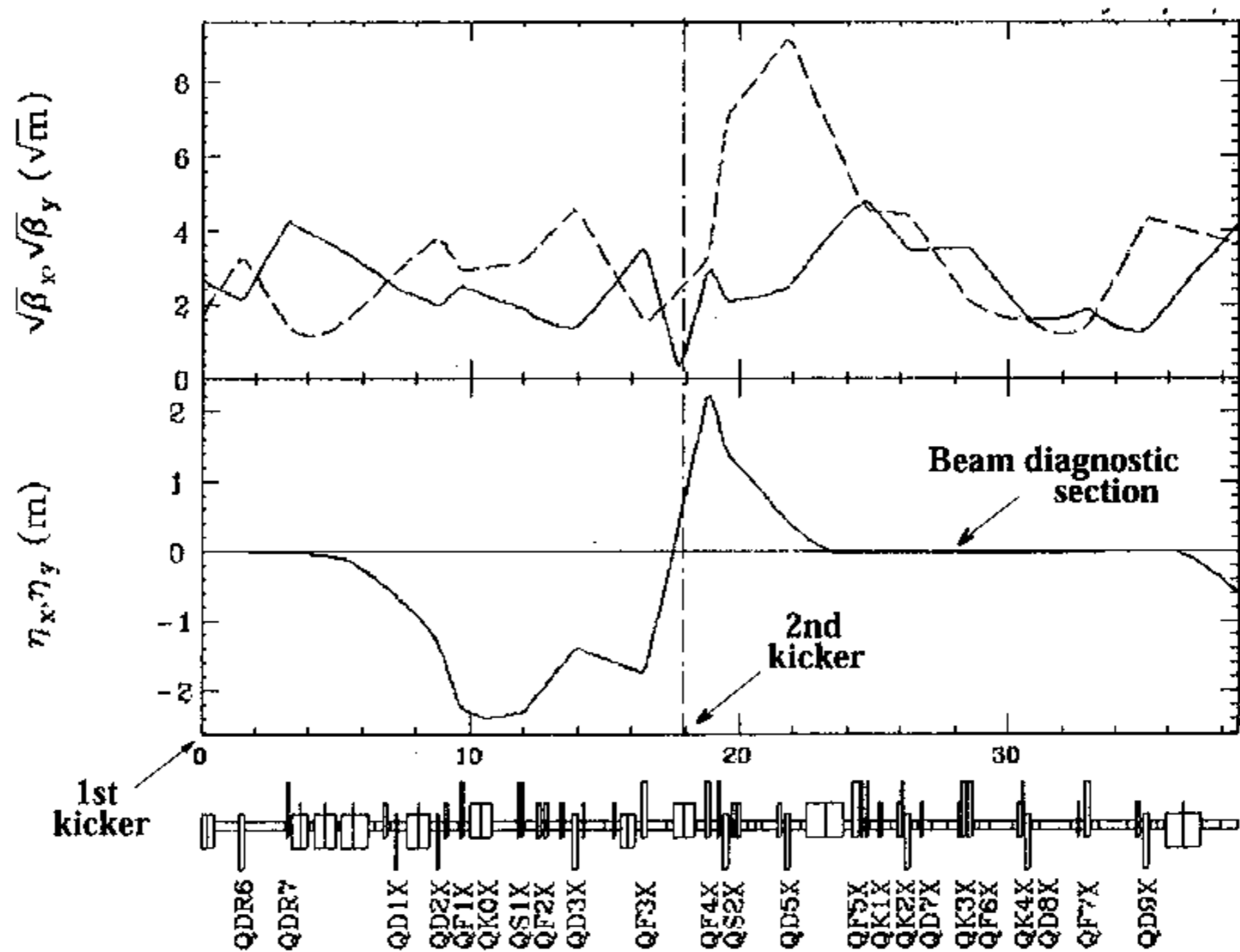


Figure 5: Optics of the extraction line;  $\beta$  function (top) and dispersion function (middle) are plotted. The solid and dotted lines show the horizontal and the vertical, respectively. It also shows the lattice from the first kicker to the end of extraction line (bottom).



